

# Design and Analysis of Sensory Informed Incomplete Block Designs

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July 12, 2012

# Incomplete Block Design

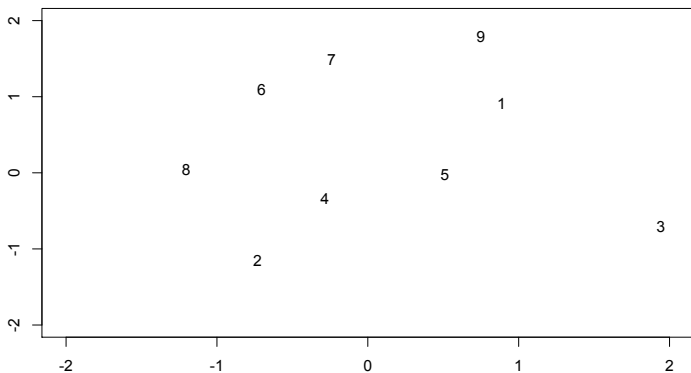
- Observe a person's response to 12 different products (randomized block design)
- However for wine and other alcohol beverages products it is difficult to obtain an individual response to several products because of intoxication, carry-over, adaption and fatigue.
- To compensate use balanced incomplete block designs.
- The goal is to determine if there is any clusters or grouping within the data.

# Sensory-Informed Design: Bread Study

## Sensory Profile

- 10-13 trained panelists
- Each panelists evaluates the 12 different Bread products on 42 attributes.
- Attributes for crumb
  - Springiness
  - Firmness
  - Moistness
  - Chewiness
  - Particles

# Products in the Sensory Space



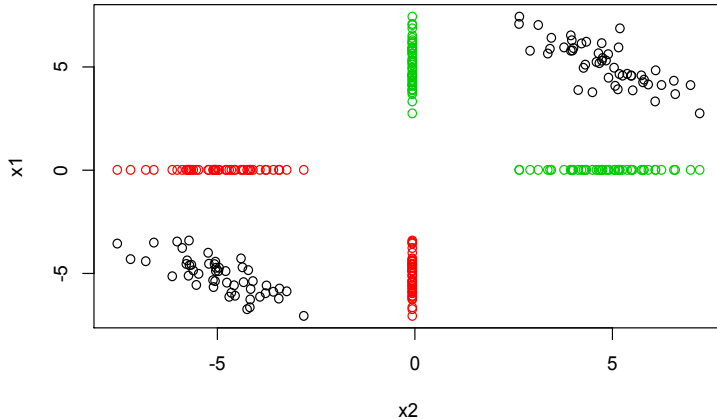
# Mixture Modelling

- To find segments in the data, we assume the liking scores arise from a Gaussian mixture

$$Y \sim \sum_{g=1}^G \pi_g f(y | \mu_g, \Sigma_g)$$

- If we had a complete-block design we would just apply standard methodology to this problem.
- The literature commonly suggests imputation or some variation thereof, for incomplete blocks.

# Imputation using the Average



# Missing Data

- However, it is possible to estimate a covariance matrix when some data are missing.
- We can do this via the expectation-maximization (EM) algorithm.
- This approach is particularly useful when the covariance matrix has a special structure.
- And even more so when

$$\Sigma_g = \Sigma$$

# Covariance Structures

- Mclust models - (Mclust in R)

$$\boldsymbol{\Sigma}_g = \lambda_g \mathbf{D}_g \mathbf{A}_g \mathbf{D}_g^T$$

- Factor Analyzers - (pgmm package in R)

$$\boldsymbol{\Sigma}_g = \boldsymbol{\Lambda}_g \boldsymbol{\Lambda}_g^T + \boldsymbol{\Psi}_g$$



# Conditional Distribution of Missing Data

- To use EM algorithm we need to calculate the sufficient statistics for the missing data.

$$X_1 | X_2 = x_2 \sim MVN(\mu_1 + \Sigma_{12} \Sigma_{22}^{-1} (x_2 - \mu_2), \Sigma_{11} - \Sigma_{12} \Sigma_{22}^{-1} \Sigma_{21})$$

- However, we have to calculate the expected sufficient statistics for the missing data in each row.
- This amounts to  $m$  choose  $k$  different matrix inverses.
- For the bread data 12 choose 6 = 920 matrix inverses.
- Complete E-steps are not computationally feasible.

# Incremental E-step or E-Step by column

- If start with the missing data  $x_i = (x_{i1}, x_{i2}, NA, NA)$  and fill in the missing data with randomly generated observations.
- For for a particular row we say  $\hat{x}_i = (x_{i1}, x_{i2}, \hat{x}_{i3}, \hat{x}_{i4})$ . So, now we have a complete dataset.
- Go by column and update each estimated observation via

$$\hat{x}_{i,j} = \mu_j + \Sigma_{j,-j} \Sigma_{-j,-j}^{-1} (\hat{x}_{i,-j} - \mu_{-j})$$

- e.g.

$$\hat{x}_3 = \mu_3 + \Sigma_{3,-3} \Sigma_{-3,-3}^{-1} (\hat{x}_{-3} - \mu_{-3})$$

where  $\hat{x}_{-3} = (x_{i1}, x_{i2}, \hat{x}_{i4})$

- If we perform this iteratively then

$$(\hat{x}_3, \hat{x}_4) \rightarrow \mu_{(3,4)} + \Sigma_{(3,4),(1,2)} \Sigma_{(1,2),(1,2)}^{-1} (x_{(1,2)} - \mu_{(1,2)})$$

## EM by column

- If we have the inverse matrix of  $\Sigma$

$$\Sigma = \begin{bmatrix} \sigma_{1,1} & \Sigma_{1,-1} \\ \Sigma_{-1,1} & \Sigma_{-1,-1} \end{bmatrix} \quad \text{and} \quad \Sigma^{-1} = \Theta = \begin{bmatrix} \theta_{1,1} & \Theta_{1,-1} \\ \Theta_{-1,1} & \Theta_{-1,-1} \end{bmatrix}$$

$$\frac{1}{\theta_{1,1}} \Theta_{1,-1} = \Sigma_{j,-j} \Sigma_{-j,-j}^{-1}$$

- This result is possible due to a relationship between the Matrix Inverse and Schur Complement of a matrix
- We now have an incremental E-step for the 1<sup>st</sup> moment.
- We can obtain a similar result for the 2<sup>nd</sup> moment.

## EM

- From Neal and Hinton (1998) the EM can be viewed as minimizing

$$F(N_{\mathbf{z}}, \mathbf{x}_i, \theta) = \log L(\mathbf{x}_i | \theta) - D_{\text{KL}}(N_{\mathbf{z}} || N_{\mathbf{z} | \mathbf{x}_i})$$

- E-step can be viewed as minimizing the Kullback-Leibler (KL) divergence between the missing data distribution and the conditional distribution of the missing data given the observed data.

# Application

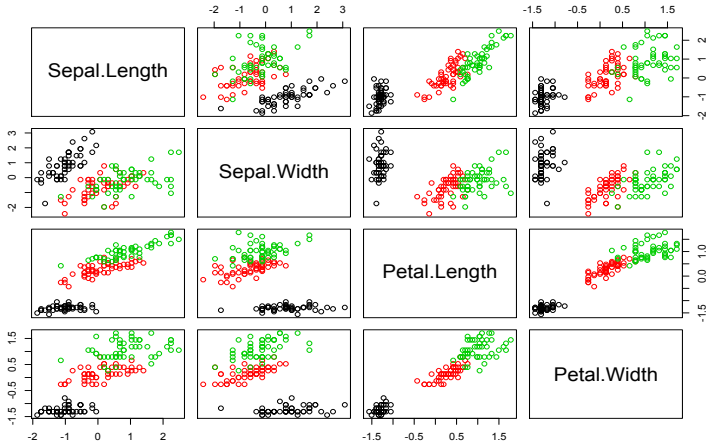
- Iris Dataset.
- Bread Dataset.

# Iris Dataset

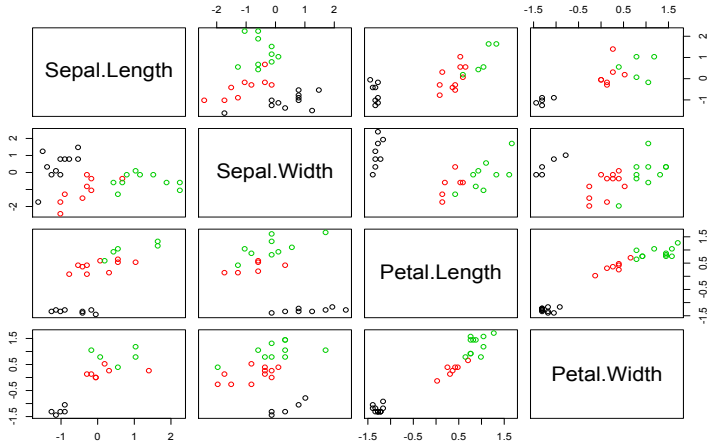
- One of the most famous data sets in statistics.
- Four measurements on three types of flowers.
- We standardized the data and for each observation we randomly removed two measurements.

<i>Sepal.Length</i>	<i>Sepal.Width</i>	<i>Petal.Length</i>	<i>Petal.Width</i>
		-1.34	-1.31
-1.14		-1.34	
	0.33		-1.31
-1.50	0.01		
		-1.34	-1.31
-0.54			-1.05
⋮	⋮	⋮	⋮

# Original Iris Dataset

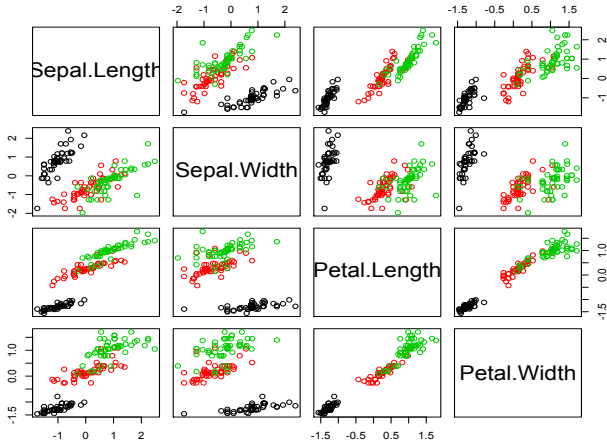


# Incomplete Iris Data

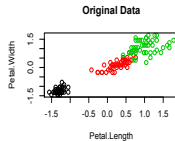
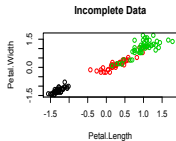
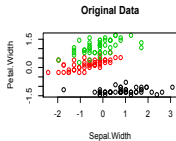
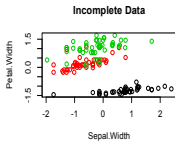
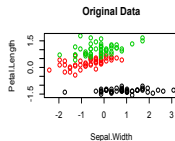
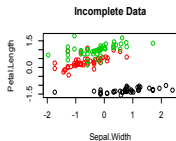
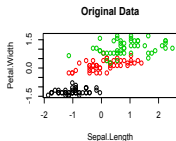
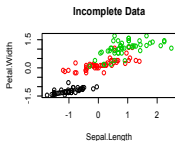
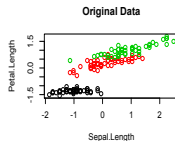
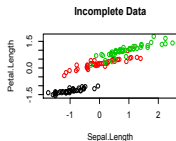
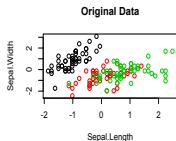
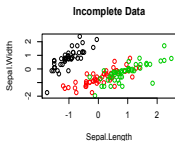




# Incomplete Iris Data with Imputed Values

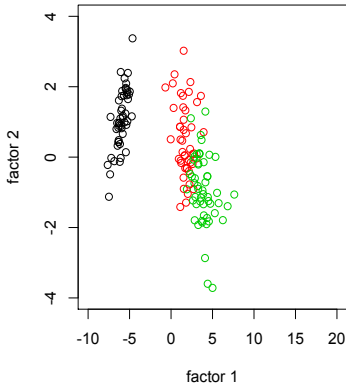


# Comparison - Imputed Incomplete and Original Data

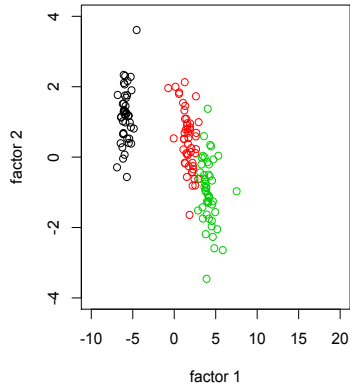


# Comparison of the Latent Space - Iris Data

## Complete Data



## Incomplete Data



# Clustering Comparison

Comparison of clustering results from using the incomplete iris data and the iris data.

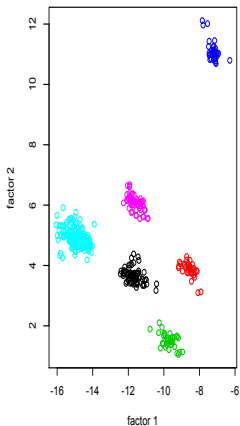
	1	2	3
1	50	0	0
2	0	47	0
3	0	3	50

# Data

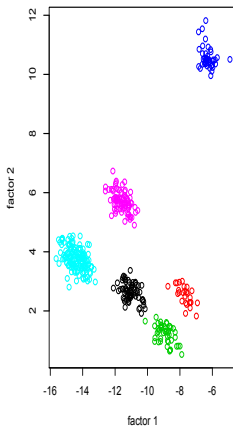
- 420 consumers.
- 12 white breads.
- Each individual evaluated 6 breads within a sensory informed incomplete block design.
- Present-3 and present-4 designs were nested within the present-6 design.
- Six groups and two factors were chosen using the Bayesian Information Criterion (BIC).

# Latent Space - Bread Liking Scores

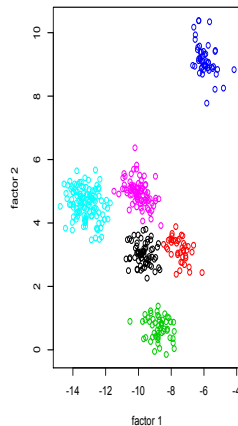
12 present 3



12 present 4



12 present 6



# Conclusions

- We can find MLEs using incremental EM.
- We can obtain a reasonable estimate of the latent space using only incomplete data.
- This methodology can be used for imputation.

# The end

Thank you.